

SERVOMOTOR

FOR REGULATION VALVE

EQUISFERA 2 o 3 WAYS

1/2" - 3/4" - 1" - 1" 1/4 - 1" 1/2



Supply voltage: 24 V AC
Proportional control

OPERATING INSTRUCTIONS

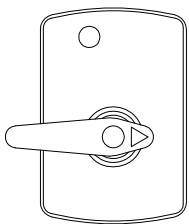
GENERAL INFORMATION

The electrical actuator is made by an electrical motor connected to a strong gear-box with steel gears. This is a reversible movement actuator, specially developed to work with the flow regulation 2-ways and flow mixing 3-ways Equisfera valves on plants with hot or cold water.

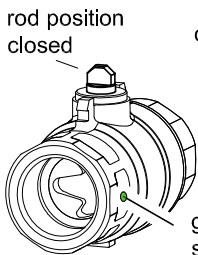
INSTALLATION

1) CHECK THAT VALVE AND SERVOMOTOR ARE BOTH IN CLOSED POSITION

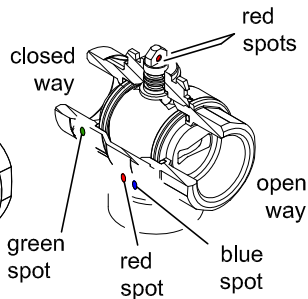
servomotor in closed position



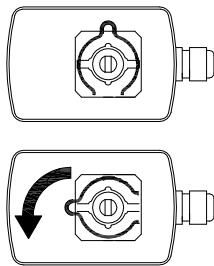
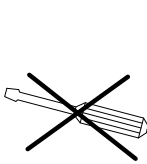
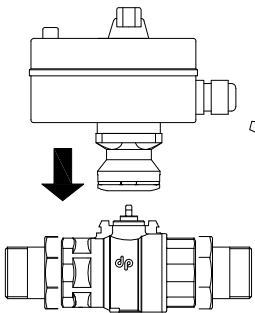
2 ways valve in closed position



3 ways valve in closed position



2) ENGAGE THE SERVOMOTOR

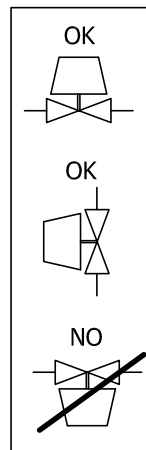


WORKING

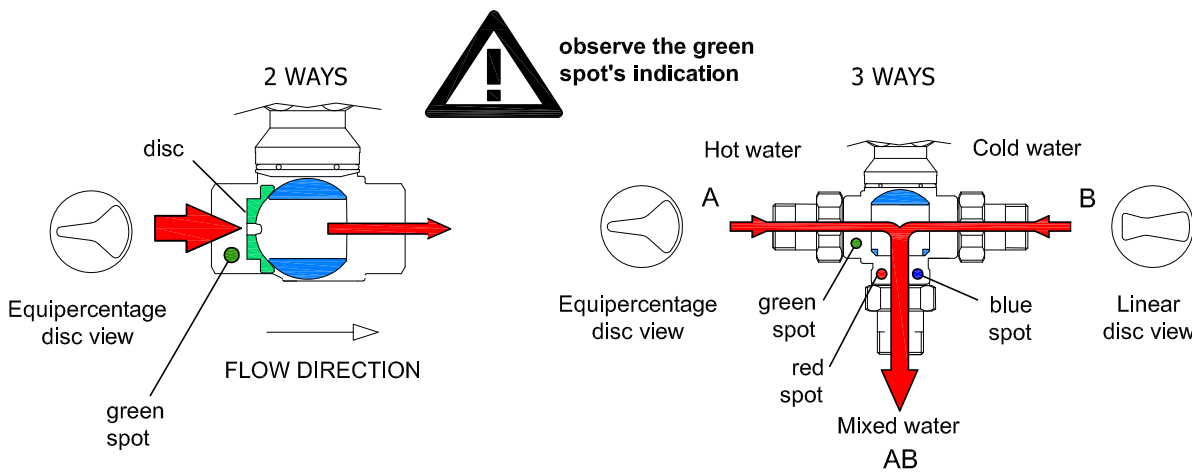
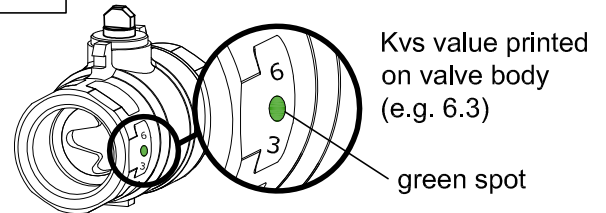
90° rotation movement of the actuator is controlled by a Vdc or mA signal. The positioning is proportional to the signal the actuator receives.

Control signal can be generated by any control unit with a modulating output signal, like a climatic regulation control, or an ambient temperature control unit.

Zero positioning sequence to define the working range: after the power supply is connected, the servomotor rotates clockwise (seen from handle side) to the end stroke position; then it moves according to the positioning signal. The zero positioning sequence is executed also if the positioning signal is zero for a few seconds (or if the signal is maximum, it depends on rotation way setting).



RELEASE PUSH BUTTON FOR MANUAL OVERRIDE
ROTATE MANUALLY ONLY
WITHOUT POWER INPUT



SERVOMOTOR

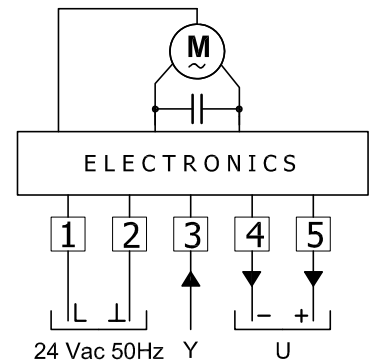
| | P7EV9V | P7EV9 | P7EV9L | P7EA9V | P7EA9 | P7EA9L |
|-----------------------------|----------------------------|-------|--------|-----------|-------|--------|
| Supply voltage | 24 V +/- 10% 50 Hz | | | | | |
| Power consumption | 5.6 VA | | | | | |
| Static torque | 9 Nm | 13 Nm | | 9 Nm | 13 Nm | |
| Working ambient temperature | 0 ÷ 50 °C | | | | | |
| Operation angle | 90° bidirectional rotation | | | | | |
| Operation time | 30" | 60" | 120" | 30" | 60" | 120" |
| Type of control | 0 - 10 V | | | 4 - 20 mA | | |
| Electrical protection level | IP65 | | | | | |

VALVE BODY

| | |
|----------------------------|--|
| Valve body | Brass CW617N Nickel plated |
| Ball | Brass CW617N Nickel/Chromium plated |
| Discs | PTFE on EPDM o-rings |
| Rod | Drawn brass CW614N with double EPDM o-rings |
| Coupling | POM-C with stainless steel ring |
| Max. operating pressure | 16 bar |
| Max. differential pressure | 4 bar |
| Fluid temperature range | 0 ÷ 110 °C |
| Operative fluid | Water or liquids which are compatible with PTFE/EPDM |

| SERVOMOTOR + 2 WAYS VALVE | |
|---------------------------|------------------------|
| DN | H A min C F P B |
| 15 | 137 143 57 77 105 131 |
| 20 | 137 143 57 77 108 139 |
| 25 | 140 146 60 87 121 156 |
| 32 | 144 150 64 94 133 172 |
| 40 | 152 158 72 108 151 193 |

| SERVOMOTOR + 3 WAYS VALVE | |
|---------------------------|---------------------------|
| DN | H A min C F B Q P |
| 15 | 137 143 57 76 130 38 65 |
| 20 | 137 143 57 76 136 38 68 |
| 25 | 141 147 61 86 155 43 78 |
| 32 | 144 150 64 94 172 47 86 |
| 40 | 152 158 72 108 193 60 102 |

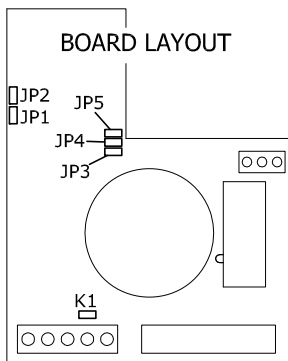


ELECTRIC CONNECTIONS

terminals 1 - 2: supply voltage 24 Vac
 terminal 3: positioning signal Y (negative pole is internally connected to terminal 2)
 terminals 4 - 5: positional feedback signal U (V)

SETTING ROTATION WAY AND TYPE OF CONTROL

DISCONNECT THE POWER SUPPLY BEFORE ANY SETTING



| Positioning signal Y | | | | |
|---|--------------------------|-------------------------------------|-------------------------------------|-------------------------------------|
| | 0 - 10 V | 2 - 10 V | 0 - 20 mA | 4 - 20 mA |
| JP2 | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| JP1 | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| K1 | <input type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| Rotation way setting with positioning signal Y increasing - (seen from handle side) | | | | |
| | CCW (default setting) | | CW | |
| JP3 | <input type="checkbox"/> | | <input checked="" type="checkbox"/> | |

not connected jumper

connected jumper

JP4, JP5 available to change the operation time

GUARANTEE

The Seller warrants each new servomotor to be free from defects in material, workmanship and construction, and that when installed and used in accordance with this technical datasheet will perform to applicable specifications for a period of two years from the date of delivery.

If examination by the Seller discloses that the product has been defective, then its obligation is limited to repair or replacement, at its option, of the defective product or its components. The Seller is not responsible for products which have been subject to misuse, alteration, accident or for repairs not performed by the Seller.

Products must be returned properly packed with transportation charges prepaid to The Seller; return delivery terms will be DDP Seller's Factory. The foregoing warranty constitutes the Seller sole liability, and is in lieu of any other warranty, of merchantability or fitness. The Seller shall not be responsible for any incidental or consequential damages arising from any breach of warranty.

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